

Rook Jumping Maze Generation for AI Education

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3	2	1	4	1
3	2	1	3	3
3	3	2	1	4
3	1	2	3	3
1	4	4	3	G

Rook Jumping Maze

- ▶ **Specification:** grid size, start state (square), goal state, jump numbers for each non-goal state.
- ▶ ***Jump number:*** Move *exactly* that many squares up, down, left, right. (*Not* diagonally.)
- ▶ **Objectives:**
 - Find a path from start to goal.
 - Find the shortest of these paths.

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The Assignments

- ▶ <http://modelai.gettysburg.edu/2010/rjmaze>
- ▶ Preliminaries:
 - [Maze Representation](#)
- ▶ Uninformed Search:
 - [Maze Evaluation](#)
 - [Maze Evaluation II](#)
- ▶ Stochastic Local Search:
 - [Hill Descent](#)
 - [Hill Descent with Random Restarts](#)
 - [Hill Descent with Random Uphill Steps](#)
 - [Simulated Annealing](#)
- ▶ Machine Learning
 - [Restart Bandit](#)
 - [Restart SARSA](#)

Preliminaries

- ▶ Maze Representation
- ▶ **Problem:** Generate and print a random n -by- n Rook Jumping Maze ($5 \leq n \leq 10$) where there is a legal move (jump) from each non-goal state.

3	2	1	4	1
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1	4	4	3	G

**ROOK
JUMPING
MAZES**

Gettysburg
COLLEGE
Department of
Computer Science

Rook Jumping Maze Representation

Rook Jumping Maze Instructions: Starting at the circled cell in the upper-left corner, find a path to the goal cell marked "G". From each numbered cell, one may move that exact number of cells horizontally or vertically in a straight line. How many moves does the shortest path have?

3	2	1	4	1
3	2	1	3	3
3	3	2	1	4
3	1	2	3	3
1	4	4	3	G

Solution (select to reveal): [19 moves: RDLRUDRLRLUULDRRUDD]

Problem: Generate and print a random n -by- n Rook Jumping Maze (RJM) ($5 \leq n \leq 10$) where there is a legal move (jump) from each non-goal state.

Let array row and column indices be $(r_{min}, \dots, r_{max})$ and $(c_{min}, \dots, c_{max})$, respectively, where $r_{max} - r_{min} + 1 = c_{max} - c_{min} + 1 = n$. The RJM is represented by a 2D-array of jump numbers. A cell's *jump number* is the number of array cells one must move in a straight line horizontally or vertically from that cell. The start cell is located at (r_{min}, c_{min}) . For the goal cell, located at (r_{max}, c_{max}) , let the jump number be zero. For all non-goal cells, the randomly generated jump number must allow a legal move. In the example 5-by-5 maze above, legal jump numbers for the start cell are {1, 2, 3, 4}, whereas legal jump numbers for the center cell are {1, 2}. In general, the minimum legal jump number for a non-goal cell is 1, and the maximum legal jump number for a non-goal cell (r, c) is the maximum of $r_{max} - r -$

Uninformed Search

▶ Maze Evaluation

- **Problem:** [Maze Representation step] Then, for each cell, compute and print the minimum number of moves needed to reach that cell from the start cell, or "--" if no path exists from the start cell, i.e. the cell is *unreachable*.
- Breadth-first search
- Print objective function: negative goal distance, or a large positive number if goal is unreachable.

Stochastic Local Search

- ▶ Maze design as search
 - Search space of possible maze designs for one that minimizes objective function.
- ▶ Stochastic Local Search (SLS):
 - [Hill Descent](#)
 - [Hill Descent with Random Restarts](#)
 - [Hill Descent with Random Uphill Steps](#)
 - [Simulated Annealing](#)
- ▶ Additional resources for teaching SLS:
<http://cs.gettysburg.edu/~tneller/resources/sls/index.html>

As You Wish...

- ▶ “I really hate this damned machine; I wish that they would sell it. / It never does quite what I want but only what I tell it.” – Anonymous
- ▶ Our maze designs are only as good as our obj. function.
 - ▶ While maximizing shortest path is a simple starting point for maze design, we can do better.
- ▶ Maze Evaluation II
 - ▶ **Problem:** Define a *better* maze objective function and argue why it leads to improved maze quality.
 - ▶ **Features:** Black/white holes, start/goal positions, shortest solution uniqueness, forward/backward branching, same-jump clusters, etc.
 - ▶ ICCG’10 paper: *Rook Jumping Maze Design Considerations*

Machine Learning

- ▶ SLS is an anytime algorithm
 - More search iterations → same/better maze design
 - When generating many mazes, how does one balance utility of computational time versus utility of maze quality?
- ▶ Restart Bandit
 - n -armed bandit MDP with # iterations as arms
 - ϵ -greedy/softmax strategy for action selection
- ▶ Restart SARSA
 - Use SARSA to map # iterations since restart and best maze evaluation to actions {GO, RESTART}

Variations

- ▶ Many variations are possible to avoid plagiarism:
 - Use different regular **tilings**, e.g. triangular or hexagonal.
 - **Topological constraints** may be added (e.g. impassable walls/tiles) or removed (e.g. toroidal wrap-around).
 - **Movement constraints** may be varied as well.
 - Add diagonal moves → Queen Jumping Maze
 - Abbott's "no-U-turn" rule increases state complexity

Conclusion

- ▶ The best puzzle assignments have a high fun to source–lines–of–code (SLOC) ratio:
 - RJMs are fun, novel, interesting mazes with simple representation and rules.
 - RJMs are particularly well suited to application of graph algorithms (evaluation) and stochastic local search (design).
- ▶ Everything you'd ever want to know about RJMs:
 - <http://tinyurl.com/rjmaze>
- ▶ Questions?